

# Lie Derivative

(1) Lie bracket:

Def: Lie algebra is v.s.  $\mathcal{L}$  with a multi-symmetric product  $[\cdot, \cdot]: \mathcal{L} \times \mathcal{L} \rightarrow \mathcal{L}$  is bilinear and satisfies Jacobi. id  $\sum_{cyc} [u, [v, w]] = 0$ .

Prmk: i) Trivial  $\mathcal{L}$ -algebra:  $[v, w] := 0$ .

ii) Jacobi. id. can be viewed as a replacement of associativity.

eg.  $\text{End}(U) = \mathcal{L}(U, U)$ , linear endomorphism on  $U$  with  $[A, B] \stackrel{\Delta}{=} A \cdot B - B \cdot A$ .

Recall  $\mathcal{X}(M)$  can be viewed as a module

on  $\mathcal{C}^\infty(M)$ :  $(fX + Y)_p \stackrel{\Delta}{=} f(p)X_p + Y_p$ .

And recall  $X \in \mathcal{X}: \mathcal{C}^\infty(M) \rightarrow \mathcal{C}^\infty(M)$ ,  
 $f(p) \mapsto (X_p f(p))_p$ .

So:  $\mathcal{X}(M) \subset \text{End}(\mathcal{C}^\infty(M)) = (\text{Aut} \cap \text{Isom.})$

Thm.  $\chi(M)$  is Lie algebra with  $[X, Y], f$   
 $\quad := X_p(Yf) - Y_p(Xf), \quad \forall f \in C^\infty(M).$

Rmk: 1)  $f \mapsto X \lrcorner Y f$ , is endomorphism of  $C^\infty(M)$ , should be thought as: taking second derivative in some direction. But it's not a. v. f.

Zu Kuhn's satisficing Leibniz:

Consider on  $M = \mathbb{R}^n$ :

$$\frac{1}{h^2} \Big|_{t=0} f(\gamma(t)) = f''(\gamma(0)) (\gamma'(0))^2 + f'(\gamma(0)) (\gamma''(0))$$

ii)  $\Sigma x, y$  is  $\mathbb{R}'$ -bilinear. But not  $\mathbb{C}(m)$ -bilinear

prop.  $\mathbb{E} f(x, y) = f_1(x) + f_2(y)$

Pf: check:  $[f x, Y] = f [x, Y]$   $g \langle Y f, x \rangle$   
 — let  $Y = g Y$ . —  $\langle Y f, x \rangle$ .

Pf: i) Check it only locally before or  
C<sub>cp</sub>.

2) Check it satisfies Leibniz rule.

prop.  $f: M^n \rightarrow N^n$ . smooth.  $X^i \in \mathcal{X}(M)$ .  $Y^i \in \mathcal{X}(N)$

$X^i$  is  $f$ -related to  $Y^i$ ,  $i=1,2$ . Then:

$[X^1, X^2]$  is  $f$ -related to  $[Y^1, Y^2]$

$$\begin{aligned} \text{Pf: } [Y^1, Y^2]_{f(p)} q &= Y^1_{f(p)}(Y^2 q) - Y^2_{f(p)}(Y^1 q) \\ &= D_p f(X^1_p)(Y^2 q) - D_p f(X^2_p)(Y^1 q) \\ &= X^1_p(Y^2_{f(p)} q) - X^2_p(Y^1_{f(p)} q) \\ &= [X^1, X^2]_p(q \circ f) \end{aligned}$$

Cor.  $\varphi: M \rightarrow N$  is diffeomorphism.

$$\begin{aligned} X^1, X^2 \in \mathcal{X}(M) &\Rightarrow \varphi_*([X^1, X^2]_p) \\ &= [\varphi_* X^1, \varphi_* X^2]_{\varphi(p)} \end{aligned}$$

Pf: Let  $Y^i = \varphi_* X^i$ . where.

Cor.  $(U, \varphi)$  is local chart.  $(\partial_i) \in \mathcal{X}(M)$

is coordinate basis.  $\Rightarrow$

$$[\partial_i, \partial_j] = 0 \quad \forall i, j.$$

$$\text{Pf: LHS} = \varphi_*^{-1}([ \frac{1}{\lambda X^i}, \frac{1}{\lambda X^j} ]) \stackrel{\text{iso.}}{=} 0$$

(2) Lie Deriv.:

1) Next  $X.f$  is directional derivation of  $f$  along the flow line of  $X$ :

$$X_p f \stackrel{Y_p(0)=X_p}{=} \frac{d}{dt} \Big|_{t=0} f(Y_p(t)) = \frac{d}{dt} \Big|_{t=0} f(\phi_t(p))$$

$$\stackrel{t=s}{\Rightarrow} X_{\phi_s(p)} f = \frac{d}{dt} \Big|_{t=s} f(\phi_t(p))$$

2) Next, if we want to derive vector field  $Y$  rather  $f \in C^\infty(M)$  along  $Y$ .

We need to overcome the problem:

$Y_2$  lives in different tangent space  $T_{q_2}M$ .

So, it's impossible to ask rate of change of  $Y_2$  along  $Y$ .

Def:  $X, Y \in \mathfrak{X}(M)$ . Lie derivative  $L_X Y$  of  $Y$  w.r.t  $X$  is defined by

$$(L_X Y)_p := \frac{d}{dt} \Big|_{t=0} (\phi_{-t})_* Y_{\phi_t p} \in T_p M.$$

where  $\phi_t$  is local flow of  $X$ .

Thm.  $X, Y \in \mathfrak{X}(M) \Rightarrow L_X Y = [X, Y]$ .

Pf: Lemma.  $X \in \mathcal{X}(m)$  with local flow  $\Phi$ :

$(-\varepsilon, \varepsilon) \times U \rightarrow m \ni p$ . Then:

$\forall f \in C^\infty(m)$ .  $\exists$  smooth  $g: (-\varepsilon, \varepsilon) \times U$

$\rightarrow \mathbb{R}$ . s.t.  $X_t f = g_t'(g)$ . And that:

$$f(\Phi_t(q)) = f(q) + t g_t'(q).$$

Pf: Let  $h_t(q) := \frac{d}{dt} f(\Phi_t(q)) = \frac{d}{dt} f(\Phi_t(q))'$

$$= \frac{d}{dt} f(X_{\Phi_t(q)}) = X_{\Phi_t(q)} f.$$

$$\text{And let } g_t'(q) = \int_0^1 h_{st}(q) ds.$$

For  $f \in C^\infty(p)$ . by Lemma.  $\exists g$ . s.t.

$$f \circ \Phi_{\pm t} = f \pm t g_{\pm t}. \quad g_0 = Xf.$$

$$\Rightarrow (L_X Y)_p f = \lim_{t \rightarrow 0} \frac{1}{t} ((\Phi_{-t}^* Y_{\Phi_t p}) f - Y_p f),$$

$$= \frac{d}{dt} \Big|_{t=0} (Y_{\Phi_t p} f) - \lim_{t \rightarrow 0} Y_{\Phi_t p} f_{-t}$$

$$= \frac{d}{dt} \Big|_{t=0} (Y f)(\Phi_t p) - Y_p f_0$$

$$= X_p(Y f) - Y_p(X f).$$